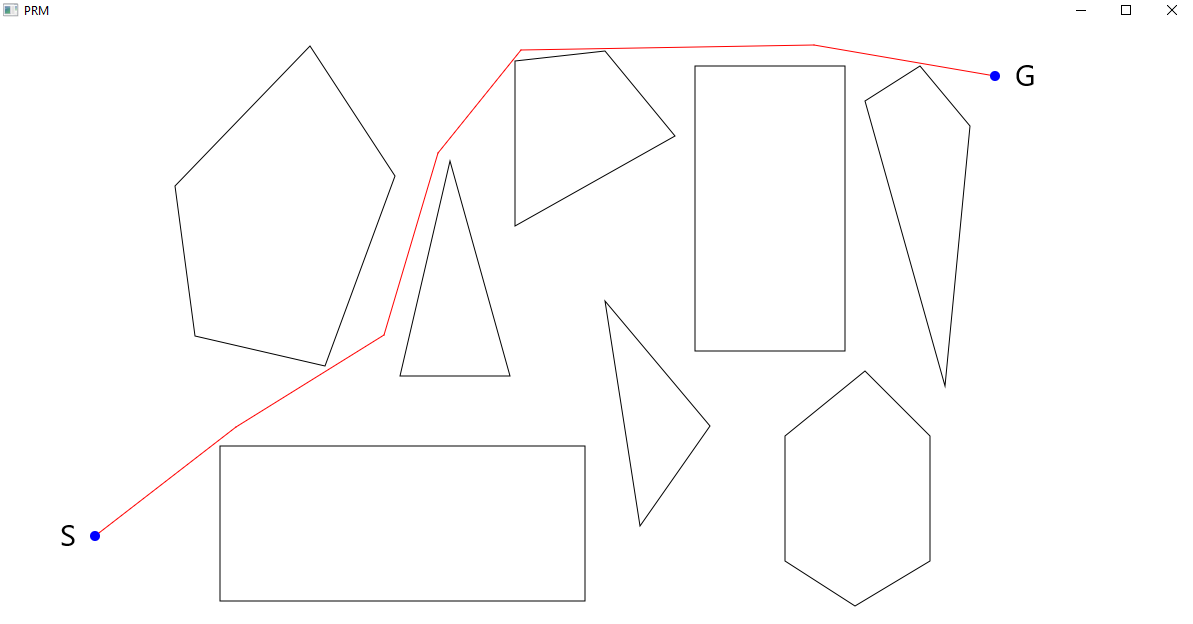
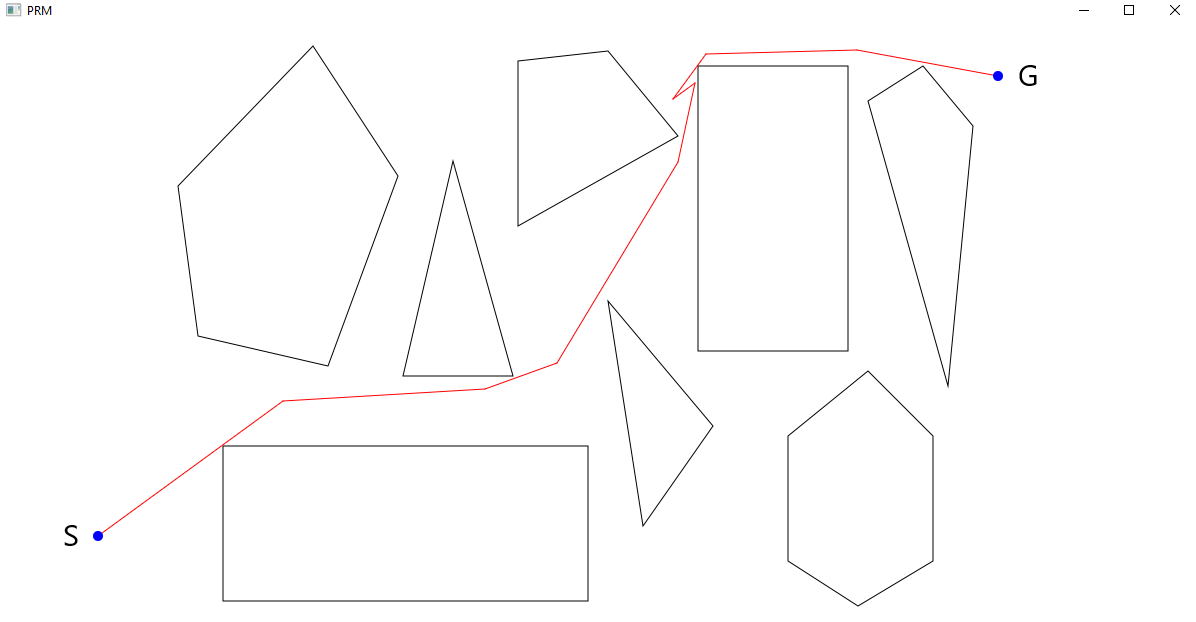
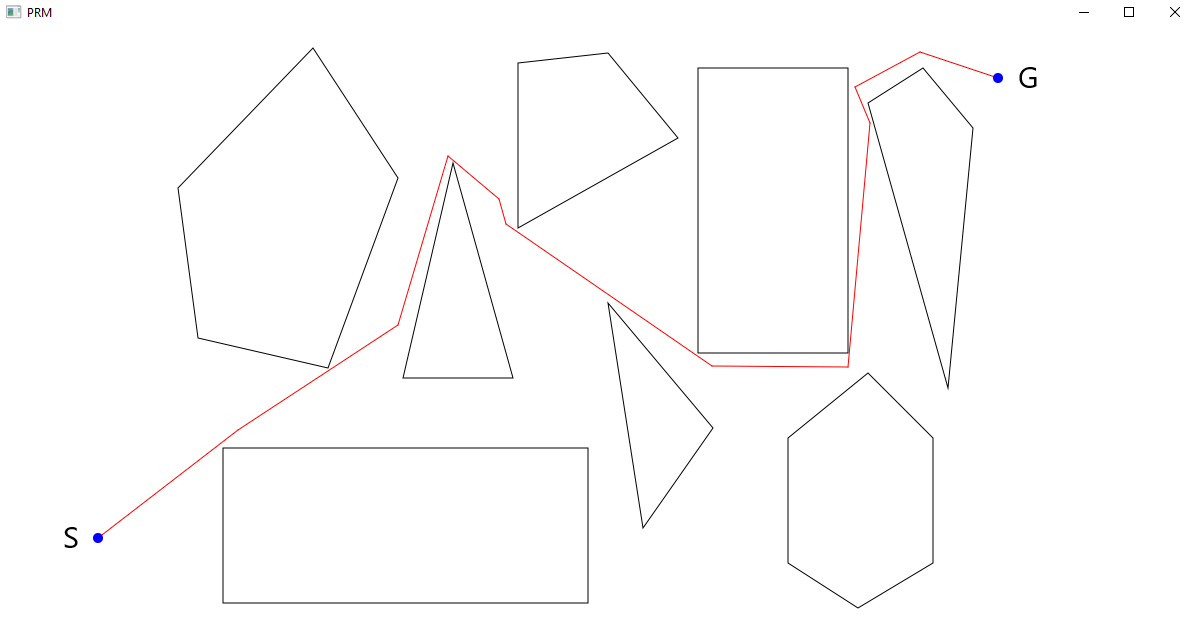
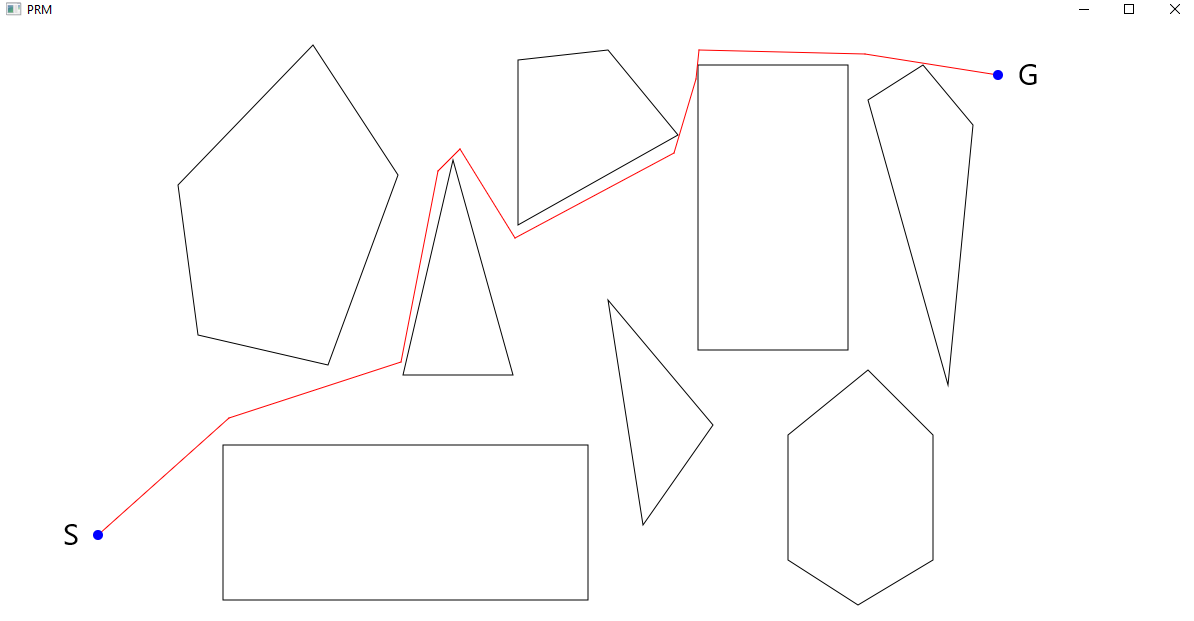
Here are some of the paths that were created using PRM. Two different environments were used. Each environment was given a different start and goal point.

Environment 1:









Environment 2:

